

	Type	L #	Hits	Search Text	DBs	Time Stamp
1	BRS	L1	258	((inertia\$1 near3 sensor) or (dead near3 reckon\$3) or acceler\$8 or gyro\$8) same phase same differen\$3 same (correct\$6 or compensat\$6) same (drift or error)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 16:09
2	BRS	L2	3	1 and triangulat\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 12:18
3	BRS	L4	30	((inertia\$1 near3 sensor) or (dead near3 reckon\$3) or acceler\$8 or gyro\$8) same phase same differen\$3 same (correct\$6 or compensat\$6) same (drift or error) same interfer\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 15:51
4	BRS	L5	228	1 not 4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 15:51
5	BRS	L6	19	((inertia\$1 near3 sensor) or (dead near3 reckon\$3) or acceler\$8 or gyro\$8) same phase same differen\$3 same (correct\$6 or compensat\$6) same (drift or error) same (antennas or receiver)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 15:52
6	BRS	L7	17	6 not 4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 15:52
7	BRS	L8	1	((inertia\$1 near3 sensor) or (dead near3 reckon\$3) or acceler\$8 or gyro\$8) same phase same differen\$3 same (correct\$6 or compensat\$6) same (drift or error) same triangulat\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 16:10
8	BRS	L9	3	((inertia\$1 near3 sensor) or (dead near3 reckon\$3) or acceler\$8 or gyro\$8) same phase same differen\$3 same (correct\$6 or compensat\$6) same (drift or error)) and triangulat\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 16:12
9	BRS	L10	7	((inertia\$1 near3 sensor) or (dead near3 reckon\$3) or acceler\$8 or gyro\$8) same phase same (correct\$6 or compensat\$6) same (drift or error)) and triangulat\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 16:12

19/025/499

BEST AVAILABLE COPY